# **Topic 9: Ordinary Differential Equation**

## 9.1 Basic Concepts and Ideas

## **Definition:**

A *differential equation* (DE) is an equation involving an unknown function and its derivatives.

Differential equations are classified according to type, order, and linearity.

## **Classification of differential equation**

An equation containing only ordinary derivatives, with respect to a *single* independent variable, is said to be an *ordinary* differential equation.

The following are differential equations involving the unknown function y.

Example 1: (i) 
$$\frac{dy}{dx} = \cos x$$
 or  $y' = \cos x$  or  $dy = \cos x dx$   
(ii)  $\frac{dy}{dx} = -\frac{x}{y}$  or  $y' = -\frac{x}{y}$  or  $dy = -\frac{x}{y} dx$   
(iii)  $x \frac{dy}{dx} - 4y = x^6 e^x$ . or  $xy' - 4y = x^6 e^x$   
(iv)  $\frac{d^2y}{dx^2} - 5\frac{dy}{dx} + 6y = 0$  or  $y'' - 5y' + 6y = 0$ 

A **partial differential equation** (or briefly a **PDE**) is a mathematical equation that involves two or more independent variables, an unknown function (dependent on those variables), and partial derivatives of the unknown function with respect to the independent variables.

*Example 2:* Here u = u(t, x) is the unknown function with two independent variables t and x.

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} \quad \text{(heat equation)}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial t^2} = 0$$
 (Laplace's equation)

## **Classification by Order**

The order of the highest-order derivative in a differential equation is called the *order* of the equation.

## **Example 3:**

$$\frac{d^2 y}{dx^2} + 5\left(\frac{dy}{dx}\right)^3 - 4y = e^x$$
$$a^2 \frac{\partial^4 u}{\partial x^4} + \frac{\partial^2 u}{\partial t^2} = 0$$

second-order ordinary differential equation.

*fourth-order* partial differential equation.

## **Classification as Linear or Nonlinear**

An ordinary differential equation is said to be linear if it can be written in the form

$$a_n(x)\frac{d^n y}{dx^n} + a_{n-1}(x)\frac{d^{n-1} y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x).$$

It is characterized by two properties:

- (i) The dependent variable y and all its derivatives are of the *first degree*; that is, the power of each term involving y is 1.
- (ii) Each coefficient depends on only the independent variable *x*.

An equation that is not linear is said to be *nonlinear*.

## **Example 4:**

$$xdy + ydx = 0$$
Linear first-order ordinary differential equation  

$$y'' - 2y' + y = 0$$
Linear second-order ordinary differential equation  

$$x^{3} \frac{d^{3}y}{dx^{3}} - x^{2} \frac{d^{2}y}{dx^{2}} + 3x \frac{dy}{dx} + 5y = e^{x}$$
Linear third-order ordinary differential equation  

$$yy'' - 2y' = x$$
Nonlinear second-order ordinary differential equation  

$$because it involves the product of y and y''.$$
Nonlinear third-order ordinary differential equation

## **Concept of Solution**

**Definition:** Any function f defined on some interval I, which when substituted into a differential equation reduces the equation to an identity, is said to be a *solution* of the equation on the interval.

## **Example 5:**

Verify that  $y = x^2$  is a solution of the differential equation (DE) xy' = 2y for all x.

## Solution:

To show that  $y = x^2$  is a solution of the DE, we have to show that the LHS of the DE is equal to the RHS. Differentiating  $y = x^2$  with respect to x and substituting y' = 2x into the LHS of the DE, we obtain

LHS = 
$$xy' = x(2x) = 2x^2$$
  
RHS =  $2y=2x^2$ 

We have an identity in *x* because LHS=RHS. Therefore  $y = x^2$  is a solution of the DE.

*Remark:* Verifying that y = f(x) is a solution of a DE is usually relatively easy as it involves differentiation. Solving a DE is much more difficult as it involves finding the unknown function y = f(x).

## **Explicit and Implicit Solutions**

A solution of an ordinary differential equation that can be written in the form y = f(x) is said to be an *explicit solution*. It is also a solution in which the dependent variable is expressed solely in terms of the independent variable and constant.

A relation G(x, y) = 0 is said to be an *implicit solution* of an ordinary differential equation on an interval *I* provided it determines implicitly a differentiable function y = f(x) that satisfies the differential equation on *I*.

#### **Example 6:**

For -1 < x < 1, show that the relation  $x^2 + y^2 - 1 = 0$  is an implicit solution of the

differential equation  $\frac{dy}{dx} = -\frac{x}{y}$ .

*Solution:* We are going to show by differentiating  $x^2 + y^2 - 1 = 0$  with respect to *x*, we

arrive at the DE 
$$\frac{dy}{dx} = -\frac{x}{y}$$
  
 $\frac{d}{dx}(x^2) + \frac{d}{dx}(y^2) - \frac{d}{dx}(1) = 0$   
 $2x + 2y\frac{dy}{dx} = 0$   
 $\frac{dy}{dx} = -\frac{x}{y}.$ 

## Example 7:

Show that the function  $y = 3xe^x$  is a solution of the linear (differential) equation

$$y'' - 2y' + y = 0$$

**Solution:** We find  $y' = 3xe^x + 3e^x$ 

$$y'' = 3xe^{x} + 3e^{x} + 3e^{x}$$
$$= 3xe^{x} + 6e^{x}$$

Therefore

$$y'' - 2y' + y = (3xe^x + 6e^x) - 2(3xe^x + 3e^x) + 3xe^x = 0$$

Hence  $y = 3xe^x$  is a solution of the DE

In general, it can be shown that  $y = Axe^{x}$ , where A is an arbitrary constant, is a solution of the differential equation y'' - 2y' + y = 0.

Hence this is known as the *general solution* of the differential equation while  $y = 3xe^x$  is a *particular solution*.

The most general function that will satisfy the differential equation contains one or more arbitrary constants; it is known as the *general solution* of the differential equation. Giving particular numerical values to one or more of the constants in the general solution results in a *particular solution* of the equation.

## Example 8:

Solve y' = cos x. Solution: y = sin x + c with arbitrary c.

Figure 1 shows some of the solutions, for c = -3, -2, -1, 0, 1, 2, 3, 4.

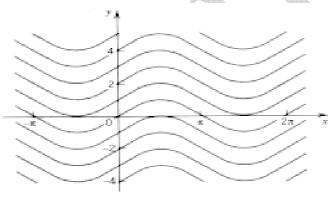


Fig. 1. Solutions of  $y' = \cos x$ 

## Initial-Value Problem

An initial value problem is an ordinary differential equation

$$F\left(x, y, \frac{dy}{dx}, \dots, \frac{d^n y}{dx^n}\right) = 0 \quad \text{(which is an nth-order differential equation)}$$

together with the initial condition

$$y(x_0) = y_0, y'(x_0) = y_1, \dots, y^{(n-1)}(x_0) = y_{n-1},$$
  
where  $x_0, y_0, y_1, \dots, y_{n-1}$  are arbitrary constants.

## **Example 9**:

1. The initial value problem. 
$$y'(x) = y$$
;  $y(0) = 3$   
2. The initial value problem  $\frac{d^2 y}{dx^2} + y = 0$ ;  $y(0) = -1$ ,  $y'(0) = 1$ .

## 9.2 Separable Differential Equations

## <u>Definition:</u>

A first-order differential equation that can be expressed in the form  $g(y)\frac{dy}{dx} = f(x) \qquad \text{or} \qquad g(y)dy = f(x)dx \qquad (1)$ 

is said to be *separable* or to have *separable variables* where f(x) is a function that depends only on x and g(y) is a function that depends only on y.

**Example 10:** Show that  $\frac{dy}{dx} = xe^{(x+2y)}$  is separable.

Solution:

$$\frac{dy}{dx} = xe^{x}e^{2y}; \qquad dy = xe^{x}e^{2y}dx;$$
$$e^{-2y}dy = xe^{x}dx$$

which is of the form g(y)dy = f(x)dx

*Example 10a:* The differential equation expressed in the form g(y)dy = f(x)dx

 $\frac{dy}{dx} = 3x - y$  is not separable because it cannot be

## Method of Solution : Separable equation

To solve a separable DE  $g(y)\frac{dy}{dx} = f(x)$  we integrate on both sides with respect to x, obtaining  $\int g(y)\frac{dy}{dx}dx = \int f(x)dx + c.$   $\int g(y)dy = \int f(x)dx + c.$ 

## Example 11:

Solve the differential equation  $\frac{dy}{dx} = 1 + y$ Solution: We note that the DE is separable because it can be expressed in the form g(y)dy = f(x)dx

$$\frac{1}{1+y}dy = dx$$
$$\int \frac{1}{1+y}dy = \int dx$$
$$\ln|1+y| = x + c$$

This is an implicit solution of the DE. It can be converted into an explicit solution of the form y = f(x). How?

## Example 12:

Solve the differential equation 9yy' + 4x = 0. Solution:

$$\frac{dy}{dx} = \frac{-4x}{9y}$$

$$\int 9y dy = -\int 4x dx$$

$$\frac{9}{2}y^2 = -2x^2 + c^*$$

$$\frac{x^2}{9} + \frac{y^2}{4} = c$$

The solution represents a family of ellipses.

## **9.3 Linear Differential Equations**

## **Definition:**

A differential equation of the form

х

$$a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

is said to be a *first-order linear equation*.

For example,

$$\frac{dy}{dx} - 4y = x^6 e^x$$

is a first order linear DE.

Here 
$$a_1(x) = x$$
,  $a_0(x) = -4$ , and  $g(x) = x^6 e^x$ 

## Method of solution : First Order Linear Differential equation

#### Example 13:

Solve

$$x\frac{dy}{dx} - 4y = x^6 e^x.$$

Solution:

- Rewrite the DE as  $\frac{dy}{dx} \frac{4}{x}y = x^5e^x$ . 1.
- We then note that  $P(x) = -\frac{4}{x}$ . Hence, the integrating factor is given by 2

+c

$$\mu(x) = e^{\int (-\frac{4}{x})dx} = e^{-4\ln x} = e^{\ln(x^{-4})} = \frac{1}{x^4} \text{ because } e^{\ln f(x)} = f(x)$$
  
$$\therefore \frac{1}{x^4} \frac{dy}{dx} - \frac{4}{x^5} y = \frac{1}{x^4} (x^5 e^x)$$

3. 
$$\therefore \frac{1}{x^4} \frac{dy}{dx} - \frac{4}{x^5} y = \frac{1}{x^5} y$$

4. 
$$\frac{d}{dx}\left(\frac{1}{x^4}y\right) = xe^x$$

5. 
$$\frac{1}{x^4} y = \int x e^x dx = x e^x - e^x$$
$$y = x^5 e^x - x^4 e^x + cx^4$$

## Example 14:

y' + 2xy = x,y(0) = 1.Solve the initial value problem:

## Solution:

P(x)=2x,Here

Integrating factor, 
$$\mu(x) = e^{\int P(x)dx} = e^{\int 2xdx} = e^{x^2}$$
.  
Multiplying into the equation,  $e^{x^2}\left(\frac{dy}{dx} + 2xy\right) = xe^{x^2}$   
 $\frac{d}{dx}\left(e^{x^2}y\right) = xe^{x^2}$   
 $e^{x^2}y = \int xe^{x^2}dx = \frac{1}{2}e^{x^2} + c$   
 $\therefore \quad y(x) = \frac{1}{2} + ce^{-x^2}$ .

From the initial condition, when x = 0, y = 1

$$\therefore \qquad 1 = \frac{1}{2} + c \qquad \text{Hence, } c = \frac{1}{2}$$
  
The solution of our initial value problem is  $y(x) = \frac{1}{2} + \frac{1}{2}e^{-x^2}$ 

## **<u>9.4 Exact Differential Equations</u>**

Revision on Partial Differentiation (Topic 8)

## Example:

Find 
$$\frac{\partial f}{\partial x}$$
 and  $\frac{\partial f}{\partial y}$  if  $f(x, y) = x^2 + 3xy + y - 1$ .

Solution: Regarding y as a constant and differentiating f(x,y) with respect to x, we obtain

$$\frac{\partial f}{\partial x} = \frac{\partial}{\partial x} \left( x^2 + 3xy + y - 1 \right) = 2x + 3y$$

Regarding x as a constant and differentiating f(x,y) with respect to y, we obtain

$$\frac{\partial f}{\partial y} = \frac{\partial}{\partial y} \left( x^2 + 3xy + y - 1 \right) = 3x + 1$$

#### Example:

Find  $\frac{\partial f}{\partial x}$  and  $\frac{\partial f}{\partial y}$  if  $f(x, y) = y \sin xy$ 

Solution:

$$\frac{\partial f}{\partial x} = \frac{\partial}{\partial x} (y \sin xy) = y \frac{\partial}{\partial x} (\sin xy) = y^2 \cos xy$$
$$\frac{\partial f}{\partial y} = \frac{\partial}{\partial y} (y \sin xy) = y \frac{\partial}{\partial y} (\sin xy) + (\sin xy) \frac{\partial}{\partial y} (y)$$
$$= y \cos xy \frac{\partial}{\partial y} (xy) + \sin xy = xy \cos xy + \sin xy$$

## Definition of Total Differential

If 
$$f = f(x, y)$$
 then the differential of  $f$ , denoted  $df$ , is defined by  

$$df = f_x(x, y)dx + f_y(x, y)dy \quad \text{or} \quad df = \frac{\partial f(x, y)}{\partial x}dx + \frac{\partial f(x, y)}{\partial y}dy$$

$$df \quad \text{is also called the total differential of } f.$$

Example: Let  $F = F(x, y) = \frac{1}{3}x^3y^3$ . Then  $dF = \frac{\partial F}{\partial x}dx + \frac{\partial F}{\partial y}dy = \frac{\partial}{\partial x}(\frac{1}{3}x^3y^3)dx + \frac{\partial}{\partial y}(\frac{1}{3}x^3y^3)dy$   $dF = x^2y^3dx + x^3y^2dy$ 

## Definition of Exact Differential Equations

A differential equation

$$M(x, y)dx + N(x, y)dy = 0$$

is said to be *exact* in a region **R** of the xy-plane if there is a function F(x, y) such that

$$\frac{\partial F(x, y)}{\partial x} = M(x, y)$$
 and  $\frac{\partial F(x, y)}{\partial y} = N(x, y)$ .

That is, the total differential of F satisfies

$$dF(x, y) = M(x, y)dx + N(x, y)dy.$$

Example 15:

1. Show that the differential equation  $x^2y^3dx + x^3y^2dy = 0$  is exact.

*Solution:* To show that the DE is exact we have to find a function F(x,y) such that its differential

$$dF = \frac{\partial F}{\partial x}dx + \frac{\partial F}{\partial y}dy = x^2 y^3 dx + x^3 y^2 dy$$

We claim that  $F(x, y) = \frac{1}{3}x^3y^3$  is such a function because  $\frac{\partial F}{\partial x} = x^2y^3$  and  $\frac{\partial F}{\partial y} = x^3y^2$ 

$$dF = x^2 y^3 dx + x^3 y^2 dy.$$

Remark : In practice, producing such a function F(x,y) to show that the DE is exact is not that easy. In fact if we can produce such a function, then the solution of the DE is given implicitly by F(x,y) = c. Later we will give an easier criterion for testing whether a given DE is exact or not.

**Example 15a:** Solve 
$$\frac{dy}{dx} = \frac{\sin y}{2y - x\cos y}$$
.

*Solution:* The above d.e. in differential form can be written as

$$\sin y \, dx + (x \cos y - 2y) dy = 0$$

To solve the DE we would have to produce a function F(x,y) such that the LHS of the above DE is dF(x,y), the total differential of F(x,y). We can verify that such a function is

$$F(x,y) = x \sin y - y^2.$$

Therefore

$$d(x\sin y - y^2) = 0$$

Hence

 $x \sin y - y^2 = c$  is the solution of the DE.

## **Theorem** (Criterion for an Exact Differential)

Let M(x, y) and N(x, y) be continuous and have continuous first partial derivatives in a rectangular region R. Then a necessary and sufficient condition that M(x, y)dx + N(x, y)dybe an exact differential is Method of solution : Exact equation If Mdx + Ndy = 0 is exact, then  $\frac{\partial F}{\partial x} = M$ . Integrate this last equation with respect to x 1.  $F(x, y) = \int M(x, y)dx + g(y) \,. \tag{2}$ to get To determine g(y), take the partial derivative with respect to y of both sides of 2. equation (2) and substitute N for  $\frac{\partial F}{\partial y}$ . We can now solve for g'(y). 3. Integrate g'(y) to obtain g(y) up to a numerical constant. Substituting g(y) into equation (2) gives F(x, y). The solution to Mdx + Ndy = 0 is given implicitly by F(x, y) = C. 4. (Alternatively, starting with  $\frac{\partial F}{\partial v} = N$ , the implicit solution can be found by first integrating with respect to y) **Example 16:** Solve  $(e^{2y} - y \cos xy)dx + (2xe^{2y} - x \cos xy + 2y)dy = 0.$ 

#### Solution:

Here  $M(x, y) = (e^{2y} - y \cos xy)$  and  $N(x, y) = (2xe^{2y} - x \cos xy + 2y)$ . Therefore  $\frac{\partial M}{\partial y} = 2e^{2y} + xy \sin xy - \cos xy = \frac{\partial N}{\partial x}$ , the equation is exact. Hence, a function F(x, y) exists for which  $M(x, y) = \frac{\partial F}{\partial x}$  and  $N(x, y) = \frac{\partial F}{\partial y}$  $\therefore \frac{\partial F}{\partial x} = e^{2y} - y \cos xy$  $F(x, y) = \int e^{2y} dx - y \int \cos xy dx = x e^{2y} - \sin xy + g(y)$  $\frac{\partial F}{\partial y} = 2xe^{2y} - x\cos xy + g'(y) = N = 2xe^{2y} - x\cos xy + 2y$ g'(y) = 2y and  $g(y) = y^2 + c$ . so that

Hence, a one parameter family of solutions is given by  $xe^{2y} - \sin xy + y^2 + C = 0.$ 

> THE END (nby, July 2016)

(2)

## **Topic 9b: Second Order Differential Equations**

## 9.5 SOLVING SECOND ORDER DIFFERENTIAL EQUATIONS

A second-order differential equation is called *linear* if it can be written as y'' + p(x)y' + q(x)y = r(x) (1) where *p*, *q*, *r* are any given function of *x*. Any *second* order differential equation that cannot be written in the above form is called *nonlinear*.

If r(x) = 0, equation (1) becomes y'' + p(x)y' + q(x)y = 0and is called *homogeneous*.

If r(x) is not identically zero, the equation is called *non-homogeneous*.

## Example 1

$y'' + 4y = e^{-x} \sin x$	non-homogeneous linear d e
$(1-x^2)y''-2xy'+6y=0$	homogeneous linear d.e
$x(y''y + y'^2) + 2y'y = 0$	homogeneous nonlinear d.e

**Theorem** (Fundamental theorem for the homogeneous equation) For a homogeneous linear differential equation (2), any linear combination of two solutions on an open interval *I* is again a solution of (2) on *I*. In particular, for such an equation, sums and constant multiples of solutions are again solutions.

## Example 2

1. Verify that  $y = e^x$  and  $y = e^{-x}$  are solutions of the homogeneous linear differential equation y'' - y = 0

2. Are  $y = ce^x$ ,  $y = de^{-x}$  and  $y = ce^x + de^{-x}$  also solutions?

Solution:

1.			
When $y = e^x$ , $y' = e^x$ and $y'' = e^x$		When $y = e^{-x}$ , $y' = -e^{-x}$ and $y'' = e^{-x}$	
Hence $y''-y = e^x - e^x = 0$		Hence $y'' - y = e^{-x} - e^{-x} = 0$	
Therefore, $y = e^x$ is a solution for the d.e.		Therefore, $y = e^{-x}$ is also a solution for the d.e.	
2.			
When $y = ce^x$ , $y' = ce^x$ and $y'' = ce^x$		When $y = de^{-x}$ , $y' = -de^{-x}$ and $y'' = de^{-x}$	
Hence $y''-y = ce^x - ce^x = 0$		Hence $y'' - y = de^{-x} - de^{-x} = 0$	
Therefore, $y = ce^x$ is a solution for the d.e.		Therefore, $y = de^{-x}$ is also a solution for the d.e.	
	$y = ce^x + de^{-x}$		
Similarly,	$y' = ce^x - de^{-x}$		
	$y'' = ce^x + de^{-x}$		
	$\therefore y'' - y = (ce^x + de^{-x}) - de^{-x} = (c$	$-(ce^x + de^{-x}) = 0$	

Therefore,  $y = ce^{x} + de^{-x}$  is another solution for the d.e.

*Note:* This theorem does not hold for the non-homogeneous equation or for a nonlinear equation.

## **General Solution**

For second-order homogeneous linear equations (2), a general solution will be of the form (3)

 $y = c_1 y_1 + c_2 y_2$ 

a linear combination of two (suitable) solutions involving two arbitrary constants  $c_1$ ,  $c_2$ . These two solutions  $(y_1 \text{ and } y_2)$  form a *basis* (or *fundamental set*) of solutions to the d.e. (2) on *I*.

## **Particular Solution**

A *particular solution* of (2) on I is obtained if we assign specific values to  $c_1$  and  $c_2$  in (3).

## **Initial Value Problem**

For second-order homogeneous linear equations, an *initial value problem* would consist of a homogeneous linear differential equation y'' + p(x)y' + q(x)y = 0and two initial conditions  $y(x_0) = K_0, y'(x_0) = K_1,$ 

## *Linear independence and dependence*

Two functions  $y_1(x)$ ,  $y_2(x)$  are said to be linearly dependent on an interval I if there exist constants  $c_1$ ,  $c_2$  not all zero, such that

 $c_1y_1(x) + c_2y_2(x) = 0$ 

for every *x* in the interval.

It is said to be *linearly independent* on an interval *I* if it is not linearly dependent on the interval.

## **Example 3**

The function  $f_1(x) = \sin 2x$  and  $f_2(x) = \sin x \cos x$  are linearly dependent on the interval  $(-\infty,\infty)$ since

$$c_1 \sin 2x + c_2 \sin x \cos x = 0$$

is satisfied for every real x if we choose  $c_1 = \frac{1}{2}$  and  $c_2 = -1$ .

## Definition of a basis

A basis of solutions of (2) on an interval I is a pair  $y_1$ ,  $y_2$  of *linearly independent* solutions of (2) on *I*.

## 9.5.1 HOMOGENEOUS EQUATIONS WITH CONSTANT COEFFICIENTS

In this section, we show how to solve homogeneous second order linear equations ay'' + by' + cy = 0(4) where the coefficients  $a(\neq 0)$ , b and c are constants.

We try a solution of the form  $y = e^{\lambda x}$ . Then  $y' = \lambda e^{\lambda x}$  and  $y'' = \lambda^2 e^{\lambda x}$ . Equation (4) becomes

$$a\lambda^2 e^{\lambda x} + b\lambda e^{\lambda x} + ce^{\lambda x} = 0$$
  
$$(a\lambda^2 + b\lambda + c)e^{\lambda x} = 0.$$

Because  $e^{\lambda x}$  is never zero for real values of x.

$$a\lambda^2 + b\lambda + c = 0$$

This latter equation is called the *auxiliary equation*, or *characteristic equation*.

The roots of the auxiliary equation are

$$\lambda_1 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}, \qquad \lambda_2 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

With that, we obtain

Case I:two real roots if  $b^2 - 4ac > 0$ Case II:a real double root if  $b^2 - 4ac = 0$ Case III:complex conjugate roots if  $b^2 - 4ac < 0$ 

Consider these three cases, namely, the solutions of the auxiliary equation corresponding to distinct real roots, real but equal roots, and a conjugate pair of complex roots.

## <u>CASE 1</u>: DISTINCT REAL ROOTS ( $\lambda_1 \neq \lambda_2$ )

The general solution of (4) on  $\mathbf{R}$  is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

where  $c_1$  and  $c_2$  are arbitrary constants.

#### Example 4

Find the general solution of y'' + 5y' + 6y = 0. Solution:

The characteristic equation is  

$$\lambda^2 + 5\lambda + 6 = 0$$
  
 $(\lambda + 2)(\lambda + 3) = 0$   
 $\lambda = -2 \text{ or } \lambda = -3$ . The roots are  $-2 \text{ and } -3$ .  
Thus, the general solution is  $y = c_1 e^{-2x} + c_2 e^{-3x}$ 

## <u>CASE II</u>: REPEATED REAL ROOTS ( $\lambda_1 = \lambda_2$ )

The general solution of (4) on  $\boldsymbol{R}$  is

$$y = c_1 e^{\lambda_1 x} + c_2 x e^{\lambda_1 x}$$

where  $c_1$  and  $c_2$  are arbitrary constants.

#### Example 5

Solve the differential equation y'' + 4y' + 4y = 0. Solution: The characteristic equation is  $\lambda^2 + 4\lambda + 4 = 0$ 

$$(\lambda + 2)^2 = 0$$
 So  $\lambda = -2$  (repeated)

Thus, the general solution is  $y = c_1 e^{-2x} + c_2 x e^{-2x}$ .

## <u>CASE III</u>: CONJUGATE COMPLEX ROOTS ( $\lambda_1$ , $\lambda_2$ are complex)

If  $\lambda_1$  and  $\lambda_2$  are complex, then we can write

 $\lambda_1 = \alpha + i\beta$  and  $\lambda_2 = \alpha - i\beta$ where  $\alpha$  and  $\beta > 0$  are real.

Therefore, the general solution of (4) on  $\boldsymbol{R}$  is

$$y = Ae^{(\alpha + i\beta)x} + Be^{(\alpha - i\beta)x}$$

which can be expressed in the following form by using Euler's formula  $e^{i\theta} = \cos \theta + i \sin \theta$ 

$$y = c_1 e^{\alpha x} \cos \beta x + c_2 e^{\alpha x} \sin \beta x$$
$$= e^{\alpha x} (c_1 \cos \beta x + c_2 \sin \beta x).$$

where  $c_1$  and  $c_2$  are arbitrary constants.

## Example 6

Find the general solution of y'' + 9y = 0. Solution:

> The characteristic equation is  $\lambda^2 + 9 = 0$  $\lambda = \pm 3i$

The general solution is  $y = c_1 \cos 3x + c_2 \sin 3x$ .

## Summary of Case I, II, and III

ay'' + by' + cy = 0 ...... (4)

r			
Case	Roots of	Basis of	General Solution of (4)
	characteristic equation	solutions of (4)	
	$a\lambda^2 + b\lambda + c = 0$		
Ι	Distinct real $\lambda_1, \lambda_2$	$e^{\lambda_1 x}, e^{\lambda_2 x}$	$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$
п	Repeated real root $\lambda = \lambda_1 = \lambda_2$	$e^{\lambda x}, xe^{\lambda x}$	$y = (c_1 + c_2 x)e^{\lambda x}$
III	Complex conjugates $\lambda_1 = \alpha + i\beta$ $\lambda_2 = \alpha - i\beta$	$e^{\alpha x} \cos \beta x,$ $e^{\alpha x} \sin \beta x$	$y = e^{\alpha x} (c_1 \cos\beta x + c_2 \sin\beta x)$ or $y = c_1 e^{\alpha x} \cos\beta x + c_2 e^{\alpha x} \sin\beta x$

## 9.5.2 NON-HOMOGENEOUS EQUATIONS WITH CONSTANT COEFFICIENTS

In this section, we show how to solve non-homogeneous linear differential equations

$$a y'' + by' + cy = r(x)$$
 (5)

where *a*,*b*, and *c* are constants and  $r(x) \neq 0$ .

The corresponding homogeneous equation of (5) is

$$ay'' + by' + cy = 0$$
 (6)

It can be shown that the *general solution* of the non-homogeneous equation (5) is given by

$$y = y_h(x) + y_p(x) \tag{7}$$

where  $y_h = c_1 y_1(x) + c_2 y_2(x)$  (also known as *complementary function*) is the general solution of the homogeneous equation (6) and  $y_p$  is a *particular solution* of (5).

Method of solving nonhomogeneous DE with constant coefficients		
Step 1:	Solve for homogeneous equation (6).	
Step 2:	Find any particular solution $y_p$ of (5).	
Step 3:	Form general solution $y = y_h + y_p$	

## Example 7

Find a particular solution of y'' + 9y = 27.

**Solution:** Since r(x) = 27 we assume that a particular solution is given by  $y_p = A$  where A is a constant. Substituting  $y_p = A$  into the above DE and noting that  $y_p'' = 0$ , we have

$$y_p$$
'' + 9  $y_p = 0 + 9 A = 27$ .

*Therefore* A = 3 *and a particular solution is given by*  $y_p = 3$ *.* 

## 9.4.2.1 Method of Undetermined coefficients

The method of undetermined coefficient is a technique for determining a particular solution  $y_p$ .

## **Rules for the Method of Undetermined Coefficients**

## (a) Basic Rule.

If r(x) is one of the functions in the first column in the table below, choose the corresponding function  $y_p$  in the second column and determine its undetermined coefficients by substituting  $y_p$  and its derivatives into (5).

Term in $r(x)$	Choice for $y_p$
$ke^{\gamma x}$	$Ce^{\gamma x}$
$kx^n (n=0,1,\cdots)$	$K_n x^n + K_{n-1} x^{n-1} + \dots + K_1 x + K_0$
$k\cos\omega x$	
$k\sin\omega x$	$\begin{cases} K\cos\omega x + M\sin\omega x \\ \end{bmatrix}$
$ke^{\alpha x}\cos\omega x$	$\alpha_{X}(K) = \alpha_{X}(K) + M + \alpha_{X}(K)$
$ke^{\alpha x}\sin\omega x$	$\bigg\} e^{\alpha x} \left( K \cos \omega x + M \sin \omega x \right)$
$x^n \cos \omega x$	$\left\{ (K_n x^n + K_{n-1} x^{n-1} + \dots + K_0) \cos \omega x + (L_n x^n + L_{n-1} x^{n-1} + \dots + L_0) \sin \omega x \right\}$
$x^n \sin \omega x$	$\int (\mathbf{A}_n x + \mathbf{A}_{n-1} x + \dots + \mathbf{A}_0) \cos \omega x + (L_n x + L_{n-1} x + \dots + L_0) \sin \omega x$

#### Example 8

Solve  $y'' + 4y' - 2y = 2x^2 - 3x + 6$ .

## Solution:

Step 1.

## We first solve the associated homogeneous equation

y'' + 4y' - 2y = 0.  
The characteristic equation is  

$$\lambda^2 + 4\lambda - 2 = 0$$
  
 $\lambda = \frac{-4 \pm \sqrt{16 + 8}}{2} = -2 \pm \sqrt{6}$ 

$$\therefore y_h = c_1 e^{(-2+\sqrt{6})x} + c_2 e^{(-2-\sqrt{6})x}$$

## Step 2. Solve for particular solution.

Since  $r(x) = 2x^2 - 3x + 6$  is a quadratic polynomial, we assume  $y_p = Ax^2 + Bx + C$ . Then  $y_p' = 2Ax + B$  and  $y_p'' = 2A$ . Substituting into the equation, we have  $2A + 4(2Ax + B) - 2(Ax^2 + Bx + C) = 2x^2 - 3x + 6$ Equating coefficients: -2A = 2, 8A - 2B = -3, 2A + 4B - 2C = 6Solving: A = -1,  $B = -\frac{5}{2}$ , C = -9 $\therefore y_p = -x^2 - \frac{5}{2}x - 9$ 

Step 3. The general solution of the given equation is

$$y(x) = y_h + y_p = c_1 e^{(-2+\sqrt{6})x} + c_2 e^{(-2-\sqrt{6})x} - x^2 - \frac{5}{2}x - 9$$

## (b) Sum Rule.

If r(x) consists of sum of *m* terms of the kind given in above table, the assumption for a particular solution of  $y_p$  consists of the sum of the trial forms  $y_{p_1}, y_{p_2}, \dots, y_{p_m}$  corresponding to these terms

$$y_p = y_{p_1} + y_{p_2} + \dots + y_{p_m}$$
.

#### **Example 9**

Find the general solution of the equation

$$\frac{d^2y}{dx^2} + 5\frac{dy}{dx} - 6y = e^{-2x} + 2 - x$$

#### Solution:

Step 1. We first solve the associated homogeneous equation The characteristic equation is  $\lambda^2 + 5\lambda - 6 = 0$   $(\lambda - 1)(\lambda + 6) = 0$   $\lambda = 1 \text{ or } \lambda = -6$  $\therefore y_h = c_1 e^x + c_2 e^{-6x}$ 

## Step 2. Solve for particular solution.

Since  $r(x) = e^{-2x} + 2 - x$  is the sum of two types of functions from the table in (a) (viz. exponential + polynomial), we assume

$$y_{p_1} = Ae^{-2x}, \ y_{p_2} = Bx + C$$
  
Let  $y_p = Ae^{-2x} + Bx + C$   
 $\therefore \quad y_p' = -2Ae^{-2x} + B$   
 $y_p'' = 4Ae^{-2x}$ 

Substituting into the equation, we have

[You are required to fill in the intermediate steps.]

$$-12A = 1, -6B = -1, 5B - 6C = 2$$
$$A = -\frac{1}{12}, B = \frac{1}{6}, C = -\frac{7}{36}$$
$$\therefore y_P = \dots$$

#### Step 3. The general solution of the given equation is

$$y = y_h + y_p = c_1 e^x + c_2 e^{-6x} - \frac{e^{-2x}}{12} + \frac{x}{6} - \frac{7}{36}$$

## (c) Modification Rule.

If a term in your choice for  $y_{p_i}$  contains terms that duplicate terms in  $y_h$ , then that  $y_{p_i}$  must be multiplied by  $x^n$ , where *n* is the smallest positive integer that eliminates that duplication.

#### Example 10

Find the general solution of the equation

$$\frac{d^2 y}{dt^2} - 2\frac{dy}{dt} + y = e^t$$

Solution:

Step 1.

We first solve the associated homogeneous equation The characteristic equation is  $\lambda^2 - 2\lambda + 1 = 0$   $(\lambda - 1)^2 = 1$  [You are required to fill in the intermediate steps.]  $\therefore y_h = c_1 e^t + c_2 t e^t$ 

```
Step 2. Solve for particular solution.

Since r(t) = e^t is a term in y_c, we assume

y_p = At^2e^t

\therefore \quad y_p' = 2At e^t + At^2 e^t

y_p''' = 2A e^t + 4At e^t + At^2 e^t

[You are required to fill in the intermediate steps.]

Substituting into the equation, we have A = \frac{1}{2}
```

Step 3. The general solution of the given equation is

$$y = y_h + y_p = c_1 e^t + c_2 t e^t + \frac{1}{2} t^2 e^t$$

## Example 11

Given that the function  $y_1(x)=e^{-5x}$  and  $y_2(x)=e^{2x}$  are both the solutions of the homogeneous equation, find the general solution of the equation

$$\frac{d^2y}{dx^2} + 3\frac{dy}{dx} - 10y = x(e^x + 1)$$

#### Solution:

Step 1. We first determine the solution of the associated homogeneous equation Since  $y_1(x)=e^{-5x}$  and  $y_2(x) = e^{2x}$  are both the solutions of the homogeneous equation  $\therefore y_h = c_1e^{-5x} + c_2e^{2x}$ 

Step 2. Solve for particular solution. Since  $r(x) = x (e^x + 1)$  is a combination of two functions, we assume

> $y_p = (Ax + B)e^x + Cx + D$  [Do you understand how the rules are applied?]  $y_p' = (Ax + B)e^x + Ae^x + C$  $y_p'' = (Ax + B)e^x + 2Ae^x$

[You are required to fill in the intermediate steps.]

Substituting into the equation, we have

$$A = -\frac{1}{6}$$
  $B = -\frac{5}{36}$   $C = -\frac{1}{10}$   $D = -\frac{3}{100}$ 

Step 3. The general solution of the given equation is  

$$y = y_h + y_p = c_1 e^{-5x} + c_2 e^{2x} + \left(-\frac{1}{6}x - \frac{5}{36}\right)e^x - \frac{1}{10}x - \frac{3}{100}$$

------THE END-----(nby, July 2016)